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Uncertainty quantification of human arterial network

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UNCERTAINTY QUANTIFICATION OF HUMAN ARTERIAL NETWORK

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Abstract: This work aims at identifying and quantifying uncertainties from various sources in human cardiovascular system based on a one dimensional arterial network. A general analysis of different uncertainties and probability characterization with log-normal distribution of these uncertainties is introduced. Deriving from a deterministic one dimensional fluid structure interaction model, we establish the stochastic model as a coupled hyperbolic system incorporated with parametric uncertainties to describe the blood flow and pressure wave propagation in the arterial network. By applying a stochastic collocation method with sparse grid technique, we study systematically the statistics and sensitivity of the solution with respect to many different uncertainties in a relatively complete arterial network validated against clinical measurements for the first time.

Keywords: uncertainty quantification, sensitivity analysis, stochastic collocation method, cardio-vascular modelling, human arterial network, wave propagation

1 Introduction

Mathematical modelling and numerical simulation of human cardiovascular system have undergone a vast development over the last few decades thanks to better understanding of the morphology and functionality of cardiovascular system, the availability of abundant clinical data as well as fast growing of computational resources [33, 21]. Specifically, various deterministic models targeted for the full human arterial tree, or specific sites (e.g. the carotid bifurcation, the aortic arch etc.), have been established [21, 2]. For instance, Navier-Stokes equations and elastic or viscoelastic equations are coupled together to characterize the fluid structure interaction property between the blood flow and the arterial wall in three dimensional configurations [21]; the one dimensional hyperbolic system simplified from the full three dimensional equations together with appropriate coupling conditions at the vascular junctions are widely used to describe the blood flow and pressure wave propagation phenomena in the arterial tree; geometrical multiscale models coupling the macrosvascular network (large arterials), mesovascular network (medium or small arterials) as well as microvascular network (arterioles or capillaries) are investigated for the hope to simulate systematically the physiological blood flow in the entire human vascular network [27, 22, 25]. Moreover, models for tissue perfusion [16], mass transfer [44], bypass design [35], electromechanical activity of the heart [12] and so on have also been developed with specific objectives. Meanwhile, various efficient computational techniques [18, 7, 21, 15] have also enhanced greatly for the cardiovascular modelling and simulation.

However, there are always discrepancies between measurements and the deterministic simulation results, since many uncertainties exist in cardiovascular system due to its complexity, diversity and

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variability [21]. For instance, the evolution of cerebral aneurysm can be influenced evidently by random external pressure or inflows [38]; the development of carotid atherosclerosis might be highly related to the inhomogeneous randomly distributed components of blood as well as the pattern of blood flow, whose geometry may be uncertain in a large degree due to the accumulation of fatty material [33]. Some of the uncertainties, namely epistemic uncertainties, can be reduced by more precise measurement or more advanced noise filtering techniques, while the other of them, namely aleatory uncertainties, are very difficult if not impossible to be accurately captured due to the inhomogeneous and multiscale properties of the cardiovascular system that undergoes an instantly and intrinsically variation owing to, for instance, the surrounding tissue pressure or external work force [21]. To identify and quantify these uncertainties, even if partially, and incorporate them into the well developed deterministic models will benefit not only for more accurate modelling and simulation of the cardiovascular system, but also for better understanding of the cardiovascular diseases. Therefore, development and analysis of efficient computational methods for uncertainty quantification becomes very important for mathematical modelling and numerical simulation of cardiovascular system.

In the modelling of the complex cardiovascular system, uncertainties are inevitably encountered from various sources and may play an important role in computational simulation. When it comes to mathematical modelling, these uncertainties may be classified in general in the following categories:

- 1. Computational geometries: Blood flow in the vascular system and the heart depends on the geometry of the blood lumen and blood vessel, which could be uncertain in a large extent, e.g., for what concerns, branch separation or bifurcation, high deflection bends, arterial wall thickness, lumen narrowed down by atherosclerosis or balloon-like bulge in the wall due to aneurysms. In fact, geometrical noise typically comes from the reconstruction of the geometry of the blood vessel with data from medical image devices, such as CT or MRI [33].
- 2. Mathematical models: There have been many mathematical models built in different geometrical scales and for different physical properties. Depending on the computational geometry, we may have multiscale models accounting for the detailed or simplified fluid velocity field and pressure with rigid or compliant walls. Based on the physical properties, we can characterize blood flow with Newtonian or non-Newtonian rheology, with or without viscoelastic or inertial properties, etc. [21]. Uncertainties thus arise from adoption of different mathematical models.
- 3. Physical parameters: When the mathematical model is established, the coefficients or physical parameters in the mathematical model is exposed to various uncertainties due to crude or unavailable measurements. The outcome of the blood flow simulation is undoubtedly determined at a certain extent by these physical parameters accounting for material properties of fluid and structure, such as the permeability, elasticity, compliance or Young's modulus of the arterial wall, the diffusivity of substance dissolved in the inhomogeneous blood solvent and so on [44].
- 4. Boundary conditions: Even for the same mathematical model and the same physical parameters, the confidence in the output of the computational simulation also depends on the uncertainties of boundary conditions prescribed on the boundary of the computational domain, including the inlet velocities or flow flux, outlet resistance or lumped parameter models, the interaction on the interface between the lumen and the arterial wall, etc [38].
- 5. External sources or forces: The transport of the main substance is carried by the blood, which also contains some other substances that make the chemical reaction between these different and contacting substances possible, resulting in increase or decrease of the substance of interest. Meanwhile, the flow rate of the blood is influenced by the surrounding tissue or uncertain distribution of external work force, which may also lead to the variation of the blood flow [21].

In order to have more precise characterization and interpretation of the cardiovascular system by mathematical modelling and numerical simulation, these uncertainties must be taken into account with different emphasis depending on the purpose. How to identify and propagate the influential uncertainties in the mathematical modelling on different levels is still at the beginning of investigation [38, 2, 43]. In fact, there is no mature techniques to characterize and represent these heterogeneous uncertainties arising from different sources, let alone systematic analysis of the influence of them to the

cardiovascular system. Preliminary work has been carried out for parametric uncertainty quantification in a local region or part of the vascular network with only one or two types of parameters [38, 43]. The authors in [38] proposed an adaptive stochastic collocation framework for uncertainty quantification and propagation in cardiovascular simulations. They studied the radius of the abdominal aortic aneurysm, the radius and inflow velocity of the carotid artery bifurcation as well as flow split of the LPA/RPA as random variables following either Gaussian or uniform distribution to account for the uncertainty impact on blood flow modelled by three dimensional Navier-Stokes equations with rigid arterial wall in a small region. A main part of the vascular network with 37 arterial segments with independent and uniformly distributed parameters for each segment was described by a one dimensional stochastic model by the authors in [43]. In particular, they considered the sensitivity of pressure with respect to the uncertainty of material parameter (e.g. Young modulus) in different segments and apply generalized polynomial chaos combined with stochastic collocation method to compute the solution.

In this work, we concentrate on and highlight the following three aspects for uncertainty quantification in the human arterial tree: 1, we first investigate several parametric uncertainties independently for time dependent sensitivity and stochastic convergence analysis; 2, and then we study systematically many different sources of parametric uncertainties (around 10) listed above at the same time and examine their distinct importance to cardiovascular simulation via global sensitivity analysis; 3, we also consider parameter dependent boundary conditions (resistance) in each distal boundary site and geometrical parameter (cross-section area) in each arterial segment obeying independent and identical probability distribution to unveil the most important region where the uncertainty is located for the quantity we are interested in. For this set of preliminary and explanatory analyses, we build a one dimensional stochastic fluid structure interaction model for the systemic arterial tree based on a one dimensional deterministic model validated by clinical measurements [34]. Although it couldn't be applied to study the local flow fields as in three dimensional modelling with detailed geometry, e.g. secondary flow, wall shear stress, vorticity of the velocity field, we are satisfied with this simplified one dimensional model for the fact that it is intrinsically a coupled hyperbolic system suitable to describe the blood flow and pressure wave propagation in the global vascular network. Moreover, we consider the vascular network with great completeness of the systemic circulation, incorporating the detailed description of the cerebral and coronary arteries, wall viscoelastic properties, wall friction and convection acceleration effect as well as realistic distal boundary conditions at the terminal sites characterized by three element windkessel model [34, 26]. These advantages enable us in a large extent to carry out more realistic uncertainty quantification in the global vascular network with many parameters.

In section 2 we summarize the deterministic fluid structure interaction model of the human arterial tree with brief description of the coupling condition and the lumped parameter model for the terminal boundary as well as the basic numerical approximation scheme. Based on the deterministic model we formulate the stochastic model in the probability framework and introduce the stochastic collocation method to solve the stochastic system. Criteria for statistical and sensitivity analysis are defined according to the representation of stochastic collocation solution. In section 3, we study the statistics and sensitivity of the solution with respect to different uncertainties in three aspects: 1, stochastic regularity and nonlinearity of the solution as well as the convergence analysis of the collocation method in the case of one dimensional parametric uncertainty; 2, systematic time averaged and time dependent sensitivity analysis of all the uncertainties over one heart beat in the case of moderate (10) dimensional parametric uncertainty; 3, quantification of the dependence of uncertainty location with independent random variables to account for uncertainty of resistance at each distal boundary and reference area in each arterial segment in the case of high (47 and 103) dimensional parametric uncertainty.

2 Mathematical modelling of the human arterial tree

2.1 Deterministic modelling: one dimensional fluid structure interaction

We introduce the simplified one dimensional deterministic fluid structure interaction model to describe the blood flow in arteries and its interaction with the blood vessel displacement following [20, 31]. In the absence of bifurcation, each segment of the arteries can be considered as a cylindrical compliant and impermeable tube with cross section S(t,x), being $t \in (0,T]$ the time and $x \in [0,L]$ the axial

coordinate. The radius r of the tube and the pressure P of the blood flow are assumed to be functions of only t and x. We also assume that the velocity u of the blood flow is dominated in the axial coordinate and depends on t, x and r with the profile $s(r,\theta) = \theta^{-1}(\theta+2)(1-r^{\theta})$, where we have $\theta=2$ for parabolic Poiseuille profile, $\theta=9$ for more physiological Womersley profile and $\theta\to\infty$ for a simple flat profile [21]. The state variables for the study of wave propagation phenomena, namely the cross-sectional area A, the volumetric flow rate Q and the average pressure P, are defined by

$$A(t,x) = \int_{S(t,x)} dS, \quad Q(t,x) = \int_{S(t,x)} u_x dS, \quad P(t,x) = \frac{1}{A} \int_{S(t,x)} PdS. \tag{2.1}$$

By integrating the three dimensional Navier-Stokes equations on a generic section S and replacing the velocity and pressure by the state variables defined in (2.1) (see [31, 21, 26] for details), we obtain the following simplified one dimensional equations governed by mass and momentum conservation law

$$\begin{cases}
\frac{\partial A}{\partial t} + \frac{\partial Q}{\partial x} = 0 & \text{in } (0, T] \times [0, L], \\
\frac{\partial Q}{\partial t} + \frac{\partial}{\partial x} \left(\alpha \frac{Q^2}{A}\right) + \frac{A}{\rho} \frac{\partial P}{\partial x} + k_r \frac{Q}{A} = 0 & \text{in } (0, T] \times [0, L],
\end{cases} (2.2)$$

where the second term and the fourth term of the momentum equation account for the convective acceleration effect and the wall friction effect, respectively. α and k_r are the Coriolis coefficient and friction coefficient defined as

$$\alpha = \frac{1}{A} \int_{S(t,x)} s^2 dS, \quad k_r = -2\pi \frac{\mu}{\rho} \frac{ds}{dr} \Big|_{r=1},$$
 (2.3)

being μ the kinematic viscosity, ρ the blood density and r=1 on the arterial wall.

In order to close the fluid system (2.2) consisting of two equations and three variables A, Q and P, we need to provide an additional relation between the pressure and the wall deformation and thus the cross section area according to certain constitutive law of the arterial wall, for instance [31]

$$P - P_{ext} = \hat{\psi}(A) + \tilde{\psi}(A) := \beta \left(\sqrt{\frac{A}{A_0}} - 1 \right) + \gamma \left(\frac{1}{A\sqrt{A}} \frac{\partial A}{\partial t} \right), \tag{2.4}$$

which incorporates not only the elastic effect in the first term but also the viscoelastic effect in the second term. The coefficients β and γ entail the physical parameters for the material property of the arterial wall in the following formula

$$\beta = \sqrt{\frac{\pi}{A_0}} \frac{hE}{1 - \nu^2}, \quad \gamma = \frac{T \tan \phi}{4\sqrt{\pi}} \frac{hE}{1 - \nu^2},$$
 (2.5)

where h, E, ν, A_0 are the wall thickness, Young modulus, Poisson coefficient and reference sectional area under only external pressure P_{ext} ; the viscoelastic parameters T and ϕ are the wave characteristic time and angle determining the viscoelasticity effect. More complex wall models can also be employed by taking into account inertia, longitudinal elasticity, etc. [20]. Initial conditions for system (2.2) can be chosen in the reference state, being $A = A_0, Q = 0$ and $P = P_{ext}$ or any other state with data extracted from either numerical simulations or clinical measurements [21].

For numerical approximation of system (2.2), we apply operator splitting techniques, decomposing the volumetric flow rate into two parts $Q = \hat{Q} + \tilde{Q}$ that account for the elastic effect and the viscoelastic effect respectively, and rewrite (2.2) for the elastic component in the conservation form [26]

$$\frac{\partial \hat{U}}{\partial t} + \frac{\partial F(U)}{\partial x} + S(U) = 0 \quad \text{in } (0, T] \times [0, L], \tag{2.6}$$

where $U = [A, Q]^T$ and $\hat{U} = [A, \hat{Q}]^T$ are the total and conservative variables, $F = [Q, F_2]^T$ are the

corresponding fluxes with

$$F_2 = \int_{A_0}^{A} \frac{A}{\rho} \frac{\partial \hat{\psi}}{\partial A} dA + \alpha \frac{Q^2}{A}, \qquad (2.7)$$

and $S = [0, S_2]^T$ consists of the friction and the non-uniformity of the geometry and the material with

$$S_{2} = k_{r} \frac{Q}{A} + \frac{A}{\rho} \left(\frac{\partial \hat{\psi}}{\partial A_{0}} \frac{\partial A_{0}}{\partial x} + \frac{\partial \hat{\psi}}{\partial \beta} \frac{\partial \beta}{\partial x} \right) - \frac{\partial}{\partial A_{0}} \int_{A_{0}}^{A} \frac{A}{\rho} \frac{\partial \hat{\psi}}{\partial A} dA \frac{\partial A_{0}}{\partial x} - \frac{\partial}{\partial \beta} \int_{A_{0}}^{A} \frac{A}{\rho} \frac{\partial \hat{\psi}}{\partial A} dA \frac{\partial \beta}{\partial x}.$$
(2.8)

As for the viscoelastic part, we obtain from system (2.2)

$$\frac{1}{A}\frac{\partial \tilde{Q}}{\partial t} - \frac{\partial}{\partial x}\left(\frac{\gamma}{\rho A^{3/2}}\frac{\partial Q}{\partial x}\right) = 0 \quad \text{in } (0, T] \times [0, L]. \tag{2.9}$$

There have been several numerical discretization schemes applied to approximate (2.6) and (2.9), e.g. second order Taylor-Galerkin [20], discontinuous Galerkin [39], spectral/hp element [43]. We choose the second order Taylor-Galerkin finite element approximation for simplicity, which is more convenient to deal with the operator splitting techniques [26]. It can be shown [31] that (2.6) is a first order nonlinear hyperbolic system so that some compatibility condition is needed to enable the computation of state variables at the first and last nodes. Moreover, the system (2.6) and (2.9) are closed by imposing valid boundary conditions, such as physiological flow rate, terminal absorbing conditions or lumped parameter models, for instance, the three element windkessels consisting of two resistors and one capacitor described by the ordinary differential equation

$$P - P_v + CR_2 \frac{dP}{dt} = (R_1 + R_2)Q + CR_1R_2 \frac{dQ}{dt} \quad \text{in } (0, T], \tag{2.10}$$

where P_v is the prescribed venous pressure, C is the capacitance and R_1, R_2 are the resistances with the common relation $R_1 = 4R/5, R_2 = R/5$ where $R = R_1 + R_2$ is the total resistance [34].

The one dimensional fluid structure interaction model (2.2) and (2.4) together with proper initial and boundary conditions is among the most popular way to describe the blood flow and its interaction with the arterial wall in each arterial segment locally [34]. In order to construct all the segments structurally and functionally to form the human arterial tree, suitable coupling conditions are needed at the bifurcations. It is demonstrated in [20] that a domain decomposition approach by keeping the mass conservation and total pressure continuity are satisfactory for characterizing blood velocity and pressure wave propagation without evident dissipation of energy in the arterial branching. More explicitly, supposing there are N_p proximal segments and N_d distal segments at a certain joint, we impose the following equations for the proximal and distal state variables (Q^p, P^p) and (Q^d, P^d)

$$\sum_{n=1}^{N_p} Q_n^p = \sum_{m=1}^{N_d} Q_m^d, \quad \text{and} \quad P_n^p = P_m^d, \, \forall \, n = 1, \dots, N_p, m = 1, \dots, N_d.$$
 (2.11)

This approach can be realized numerically by nonlinear Richardson strategy, using Newton or inexact Newton method combined with Broyden algorithm for updating Jacobian matrix, see [26] for details.

2.2 Stochastic modelling: quantifying uncertainties

As introduced in section 1, there are many different kinds of uncertainties arising from diverse sources of the human arterial tree with distinct features. Among several possible approaches to describe these uncertainties, e.g., evident theory, fuzzy set theory, probability theory, the latter ones provide a general framework to characterize various uncertainties more precisely in a quantitative way [6, 4]. Given a complete probability space $(\Omega, \mathcal{F}, \mathcal{P})$, which consists of the set of outcomes Ω , the σ -algebra of events \mathcal{F} and a probability measure $\mathcal{P}: \mathcal{F} \to [0, 1]$, we can define a random variable $Y: \Omega \to \mathbb{R}$ such that for every Borel set $B \subset \mathbb{R}$ we have $Y^{-1}(B) = \{\omega: Y(\omega) \in B\} \in \mathcal{F}$. Provided that the random variable depends also on temporal or spatial coordinate, we have stochastic process or

random fields [6]. The stochastic system of the one dimensional fluid structure interaction model corresponding to the deterministic system (2.6), (2.9) and (2.10) becomes: find the stochastic state processes $(A, Q, P) : (0, T] \times [0, L] \times \Omega \to \mathbb{R}^3$, such that \mathcal{P} -almost surely the following equations hold with proper initial boundary conditions:

$$\begin{cases}
\frac{\partial \hat{U}}{\partial t}(t, x, \omega) + \frac{\partial F(U)}{\partial x}(t, x, \omega) + S(U)(t, x, \omega) = 0 & \text{in } (0, T] \times [0, L] \times \Omega, \\
\frac{1}{A} \frac{\partial \tilde{Q}}{\partial t}(t, x, \omega) - \frac{\partial}{\partial x} \left(\frac{\gamma}{\rho A^{3/2}} \frac{\partial Q}{\partial x}\right)(t, x, \omega) = 0 & \text{in } (0, T] \times [0, L] \times \Omega, \\
P(t, \omega) - P_v + CR_2 \frac{dP}{dt}(t, \omega) = (R_1 + R_2)Q(t, \omega) + CR_1R_2 \frac{dQ}{dt}(t, \omega) & \text{in } (0, T] \times \Omega.
\end{cases}$$
(2.12)

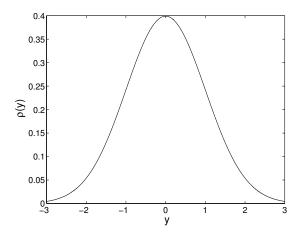
For each realization $\omega \in \Omega$, we assume that the stochastic system (2.12) shares the same mathematical properties as its deterministic counterpart, in particular, being still a hyperbolic system. The stochasticity of the state variables is propagated from the random inputs accounting for the uncertainties of involved parameters in the system, including the geometrical parameters, physical parameters as well as parameters arising from boundary conditions and external pressure. These parameters can be either represented by random variables or stochastic processes following certain probability distributions. In order to calibrate the probability distributions from various data sources such as literatures, measurements or experts' opinions, we may employ statistical inference techniques, for instance, linear and nonlinear regression, maximum likelihood estimation, maximum entropy, etc. [17, 41].

In the absence of sufficient data for calibration, we assume a general log-normal distribution for the parametric uncertainties with two considerations: 1, the deterministic value available in the literature, e.g. [34], is the most likely value with high probability (close to the expectation) while the value far from this center has low probability (with small deviation), for which normal or log-normal distribution qualifies by the maximum entropy theory [17]; 2, the parametric uncertainties should not change the sign of the parameter value, i.e. the probability to change the sign should be (or be close to) zero, for which the log-normal distribution is more appropriate since its image is \mathbb{R}_+ . Without loss of generality, we assume the random parameter perturbed by a log-normal distributed random variable

$$\eta(t, x, \omega) = e^{\mu_e + \sigma_v Y(\omega)} \eta(t, x), \tag{2.13}$$

where $\eta(t,x)$ is the deterministic parameter under consideration, which might depend on time and space, and $\eta(t,x,\omega)$ is the randomized parameter; Y is a random variable obeying standard normal distribution, which is transformed by two prescribed parameters μ_e, σ_v to a log-normal random variable as $X(\omega) = \exp(\mu_e + \sigma_v Y(\omega))$ with expectation $\mathbb{E}[X] = \exp(\mu_e + \sigma_v^2/2)$, variance $\mathbb{V}[X] = (\exp(\sigma_v^2) - 1) \exp(2\mu_e + \sigma_v^2)$, standard deviation $\mathbb{S}[X] = \sqrt{\mathbb{V}[X]}$ and the mode $\exp(\mu_e - \sigma_v^2)$ (where the density function is maximized). Figure 2.1 displays the probability density functions of the random variable Y following standard normal distribution (left) and the transformed random variable X following log-normal distribution with different values of the parameter μ_e, σ_v (right), which represent different degrees of uncertainty characterized by signal-to-noise ratio (SNR= $\mathbb{E}[X]/\mathbb{S}[X]$ [9]). We choose the mode as 1 so that $\mu_e = \sigma_v^2$ to guarantee that the deterministic value of parameter η has the highest probability. For the choice $\mu_e = 0.01, \sigma_v = 0.1$ we have SNR ≈ 9.975 , or the noise-to-signal ratio $1/\text{SNR} \approx 10\%$, for $\mu_e = 0.0625, \sigma_v = 0.25$, we have $1/\text{SNR} \approx 25.4\%$ and $\mu_e = 0.25, \sigma_v = 0.5$, we have a relatively large noise-to-signal ratio $1/\text{SNR} \approx 53.3\%$.

Supposing that the random inputs can be represented by K random variables $Y=(Y_1,\ldots,Y_K)$ with joint probability density functions $\rho(Y)=\Pi_{k=1}^K\rho_k(Y_k)$ calibrated from available data, we have that the stochastic state processes depend on the uncertainties only through Y in the image $\Gamma:=Y(\Omega)$, i.e. $(A,Q,P):(0,T]\times[0,L]\times\Gamma\to\mathbb{R}^3$. In another word, we can view the stochastic system (2.12) as a parametrized system. Therefore the random realization $\omega\in\Omega$ in (2.12) can be replaced by the parameter $y\equiv Y(\omega)\in\Gamma$ and to solve the stochastic system (2.12) is equivalent to solve a deterministic system at each parameter $y\in\Gamma$. The transformation from stochastic system to parametric system is the starting point for the application of fast stochastic computational methods that have been developed recently, including stochastic collocation method [42, 3], stochastic Galerkin method [6], reduced basis method [8], spectral decomposition method [30], low rank tensor Krylov



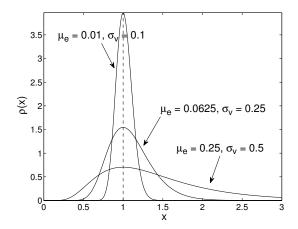


Figure 2.1: Left, standard normal density function; right, several log-normal density functions

subspace method [24] and so on. Provided that the solution of the parametric system is smooth enough with respect to the parameter y, these methods have been proved to achieve exponential or sub-exponential convergence rate, much faster than the algebraic convergence rate $N^{-1/2}$ of Monte-Carlo method [19]. Moreover, stochastic collocation method, similar to Monte-Carlo method, turns out more applicable for nonlinear and complex system due to its non-intrusive feature that enables us to use the deterministic solver directly and repeatedly without mathematical reformulation [5, 13].

Given the collocation points in $\Gamma \subset \mathbb{R}$, e.g., $-\infty < y^0 < y^1 < y^2 < \cdots < y^N < \infty$ as well as the corresponding functions $f(y^n), 0 \le n \le N$ (state variables (A, Q, P) in our context), we define the univariate Nth order Lagrangian interpolation

$$\mathcal{U}_N f(y) = \sum_{n=0}^{N} f(y^n) l^n(y), \quad \text{where } l^n(y) = \prod_{m \neq n} \frac{y - y^m}{y^n - y^m} \quad 0 \le n \le N.$$
 (2.14)

Rewrite the univariate interpolation formula (2.14) with the index k for the kth dimension as

$$\mathcal{U}_{N_k} f(y_k) = \sum_{y_k^{n_k} \in \Theta^k} f(y_k^{n_k}) l_k^{n_k}(y_k), \text{ where } \Theta^k = \{ y_k^{n_k} \in \Gamma_k, n_k = 0, \dots, N_k \} \text{ for some } N_k \ge 1 \quad (2.15)$$

then the multivariate interpolation is given as the tensor product of the univariate interpolation

$$(\mathcal{U}_{N_1} \otimes \cdots \otimes \mathcal{U}_{N_K}) f(y) = \sum_{y_1^{n_1} \in \Theta^1} \cdots \sum_{y_K^{n_K} \in \Theta^K} f(y_1^{n_1}, \dots, y_K^{n_K}) (l_1^{n_1}(y_1) \otimes \cdots \otimes l_K^{n_K}(y_K)).$$
(2.16)

In order to alleviate the "curse of dimensionality" in the interpolation on the full tensor product grid for high dimensional problems, we employ the Smolyak sparse grid interpolation that considerably reduces the number of the total collocation nodes by removing most of the cross-dimensional collocation nodes in an optimizing way while keeping high order interpolation in each dimension [40]. It achieves fast convergence rate without much sacrifice of accuracy compared to the same level of the full tensor product interpolation, in particular for analytic problem, and is proven to be one of the most efficient and widely used stochastic collocation methods [42, 29]. The general Smolyak formula reads

$$S_q f(y) = \sum_{q-K+1 \le |i| \le q} (-1)^{q-|i|} \begin{pmatrix} K-1 \\ q-|i| \end{pmatrix} \left(\mathcal{U}^{i_1} \otimes \cdots \otimes \mathcal{U}^{i_K} \right) f(y), \tag{2.17}$$

where $|i| = i_1 + \cdots + i_K$ with the multivariate index $i = (i_1, \dots, i_K)$ defined via the two possible sets

$$X_s(q,K) := \left\{ i \in N_+^K, \forall i_k \ge 1 : \sum_{k=1}^K i_k \le q \right\} \text{ or } X_p(q,K) := \left\{ i \in N_+^K, \forall i_k \ge 1 : \prod_{k=1}^K i_k \le q \right\}$$
 (2.18)

and the set of collocation nodes of the sparse grid is thus collected as

$$H(q,K) = \bigcup_{q-K+1 < |i| < q} \left(\Theta^{i_1} \times \dots \times \Theta^{i_K} \right), \tag{2.19}$$

where $\#\Theta^{i_k}=1$ if $i_k=1$, and $\#\Theta^{i_k}=2^{i_k-1}+1$ when $i_k>1$ in a nested structure. Note that we denote $\mathcal{U}^{i_k}\equiv\mathcal{U}_{N_k}$ defined in (2.15) for $N_k=2^{i_k-1}$. We define q-K as the level of interpolation. Figure 2.2 depicts the full tensor product grid, sparse grid with index sets $X_s(q,K)$ and $X_p(q,K)$ with collocations nodes defined as Gauss-Hermite quadrature abscissas [11] for two independent random variables obeying standard normal distribution, from which we can observe a large reduction of the total number of collocation nodes, especially for the sparse grid with index set $X_p(q,K)$. More advanced techniques, such as anisotropic sparse grid [28], sparse grid constructed via hierarchical surplus [23] and reduced basis [13], have been developed by taking advantage of stochastic regularity and a posteriori error estimate for further reduction of the computational cost.

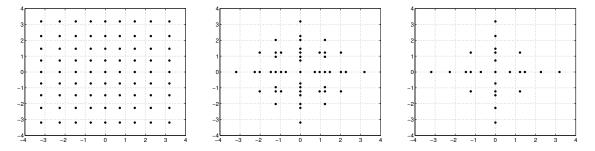


Figure 2.2: Two dimensional (K = 2) full tensor product grid (left, 81 nodes) and sparse grid with index set $X_s(q, K)$ (middle, 49 nodes) and index set $X_p(q, K)$ (right, 25 nodes), all the collocation nodes are chosen as Gauss-Hermite quadrature abscissas with the level of interpolation q - K = 3

By repeatedly solving a deterministic system at each collocation node (2.19), we can construct an explicit formula for the stochastic state variables at any parameter $y \in \Gamma$ via the sparse grid interpolation (2.17). In practice, we are more interested in the evaluation of the statistics of the state variables, such as expectation or variance, which can be computed straightforwardly as

$$\mathbb{E}[f] \approx \mathbb{E}[\mathcal{S}_q f] = \int_{\Gamma} \mathcal{S}_q f(y) \rho(y) dy = \sum_{q=K+1 \le |i| \le q} (-1)^{q-|i|} \binom{K-1}{q-|i|} \mathbb{E}\left[\left(\mathcal{U}^{i_1} \otimes \cdots \otimes \mathcal{U}^{i_K}\right) f\right]$$
(2.20)

where the tensor product expectation can be evaluated by the following quadrature formula

$$\mathbb{E}[(\mathcal{U}_{N_1} \otimes \cdots \otimes \mathcal{U}_{N_K}) f] = \sum_{y_1^{n_1} \in \Theta^1} \cdots \sum_{y_K^{n_K} \in \Theta^K} f(y_1^{n_1}, \dots, y_K^{n_K}) (w_1^{n_1} \times \cdots \times w_K^{n_K}), \tag{2.21}$$

being $(y_k^{n_k}, w_k^{n_k}), 1 \le k \le K$ the quadrature abscissas and weights according to the joint probability distribution function and $\mathcal{U}_{N_k} \equiv \mathcal{U}^{i_k}, 1 \le k \le K$. The evaluation of variance is computed by

$$\mathbb{V}[f] = \mathbb{E}\left[(f - \mathbb{E}[f])^2 \right] \approx \mathbb{E}\left[\mathcal{S}_q f^2 \right] - \left(\mathbb{E}[\mathcal{S}_q f] \right)^2. \tag{2.22}$$

In order to improve the accuracy of the numerical integral in (2.20) and the numerical interpolation

in (2.17), it is favourable to select the collocation points as the quadrature abscissas. Available quadrature rules include Clenshaw-Curtis quadrature (with Chebshev Gauss Lobatto nodes), Gaussian quadrature based on various orthogonal polynomials and so on [32, 29].

Another interest is to study the sensitivity of the state variables with respect to different parameters, or in another word, how the solution depends on each parameter at some realization $y \in \Gamma$, namely local or pointwise sensitivity analysis [36], as well as how much weight that the uncertainty arising from each parameter contributes to the total variation of the solution in the name of global sensitivity analysis [37, 10]. In the uncertainty quantification of the human arterial tree, we are more interested in how different parameters affect the blood flow and pressure wave propagation systematically, therefore, the global sensitivity analysis. Following [10], we define the variance based global sensitivity index - main effect of the kth parameter as

$$\mathbb{G}_k[f] = \frac{\mathbb{V}[\mathbb{E}[f|y_k]]}{\mathbb{V}[f]}, \quad k = 1, \dots, K,$$
(2.23)

where $\mathbb{V}[\mathbb{E}[f|y_k]]$ is the variance of the expectation of the variable f conditioned on the kth parameter y_k , accounting for the contribution to the total variance of the solution by this parameter. More explicitly, it can be evaluated approximately via the sparse grid interpolation by

$$\mathbb{V}[\mathbb{E}[f|y_k]] \approx \int_{\Gamma_k} \left(\int_{\Gamma_k^*} \mathcal{S}_q f(y) \rho(y_k^*) dy_k^* \right)^2 \rho(y_k) dy_k - \left(\int_{\Gamma} \mathcal{S}_q f(y) \rho(y) dy \right)^2, \tag{2.24}$$

where y_k is the kth element of y in one dimensional parameter space Γ_k and y_k^* is the adjoint counterpart or all the other elements of y, a K-1 dimensional parameter living in the parameter space Γ_k^* . The advantage of (2.23) attributes to its ability to measure the relative importance of different parameters and thus provide a guide for the effort (spent on collecting data, selecting statistical inference techniques, etc.) to quantify the uncertainty arising from each of them.

3 Some numerical results and analysis

3.1 Set up of simulation

We take the one dimensional human arterial tree with schematic representation from [34], see Figure 3.1 for details. It represents the main systemic arterial tree with great completeness, including the aortic arch and the coronary network, the principal abdominal aorta branches as well as the cerebral arterial tree. There are 103 segments in the arterial tree, indexed from 1 to 103, thus 103 one dimensional fluid structure interaction models (2.2) coupled together at the junctions by (2.11). Each of the 47 distal boundaries are described by one lumped parameter model (2.10). At the proximal boundary of Ascending aorta 1 (1), a physiological flow rate over one heart beat of 0.8 second is imposed as the boundary condition. The value of geometrical parameters including arterial segment length and lumen diameter as well as the terminal resistance and compliance are set according to the data presented in [34]. The parameter θ for the velocity profile is set to 9, leading to a more physiological Womersley flow. Poisson coefficient $\nu = 0.5$ represents an incompressible arterial wall. Wall thickness h, Young modulus E, characteristic time T and characteristic angle ϕ are chosen the same as in [26].

For physiological considerations, we are mainly interested in the blood flow rate and pressure at the following 18 representative locations (8 in the cerebral arterial tree and 10 in the main arterial tree) marked with circle in Figure 3.1: Right coronary RCA (96), Ascending aorta 2 (95), Left common carotid (15), Left radial (22), Abdominal aorta A (28), Left external iliac (44), Right anterior tibial (55), Right femoral (52), Thoracic aorta A (18), Right subclavian B, axillary, brachial (7), Middle cerebral M1 (73), Right ant. cerebral A2 (76), Right ant. choroidal (100), Right post. cerebral 2 (64), Basilar artery 2 (56), Right vertebral (6), Left internal carotid (16), Left ophthalmic (82).

We implement the solver for the coupled stochastic system (2.12) based on the deterministic solver implemented in LifeV [1], a parallel library written in C++, for the one dimensional fluid structure

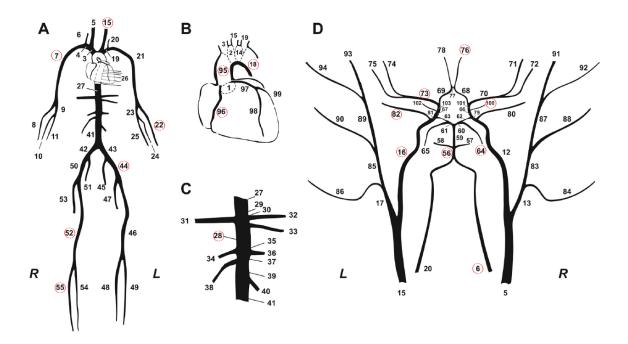


Figure 3.1: Schematic representation of the human arterial tree, taken from [34]. A: main systemic arterial tree. B: detail of the aortic arch and the coronary network. C: detail of the principal abdominal aorta branches. D: blown-up schematic of the detailed cerebral arterial tree, connected via the carotids (segments 5 and 15) and the vertebrals (segments 6 and 20) to the main arterial tree. R: right; L: left.

interaction model of the human arterial tree. The spatial and temporal discretization are specified as 2 mesh elements for 1 centimeter and 2 milliseconds per time step, respectively. Piecewise linear polynomial functions are used as the finite element bases. The output of blood flow rate and pressure is taken in the time interval of the sixth heart beat (4.0 - 4.8 seconds), when the simulation reaches a relatively stable periodic state. Although the discretization has been rather crude in order to reduce the computational time, it is fine enough to capture the right wave propagation phenomena accurately compared to a finer discretization presented in [26]. It takes around 25 minutes to run the simulation for six heart beats by 16 processors (Intel Xeon Nehalem 2.66 GHz). Thanks to the non-intrusive property of the stochastic collocation method, we can run the stochastic simulation at each random realization or collocation node in a complete parallel structure. For instance, it takes around 50 hours to run the stochastic simulations with the second level of interpolation for 10 random variables or the first level of interpolation for 103 random variables by 10×16 processors.

3.2 One dimensional parametric uncertainty

The boundary conditions - prescribed physiological flow rate Q(t) and terminal resistance at different locations R(location), the geometrical parameter - reference area of the arterial wall $A_0(x)$, the physical parameter - Young modulus E(x) and many other parameters, are different among people of different ages, sizes, genders and other factors. Even for the same person, these parameters may vary according to the work effort, healthy state, etc. In this section we study independently the uncertainty effect of these parameters to the blood flow and pressure wave propagation with different degrees of uncertainties. We first define the a posteriori error of the statistics (expectation and standard deviation) approximated by the stochastic collocation method in level l = q - K (2.17) as

$$\operatorname{error}(\mathbb{E}_{l}[f]) = \frac{||\mathbb{E}[\mathcal{S}_{q+1}f] - \mathbb{E}[\mathcal{S}_{q}f]||}{||\mathbb{E}[\mathcal{S}_{q+1}f]||}, \quad \operatorname{error}(\mathbb{S}_{l}[f]) = \frac{||\mathbb{S}[\mathcal{S}_{q+1}f] - \mathbb{S}[\mathcal{S}_{q}f]||}{||\mathbb{S}[\mathcal{S}_{q+1}f]||}, \quad (3.1)$$

where the norm ||v|| is space and time averaged value of the quantity v.

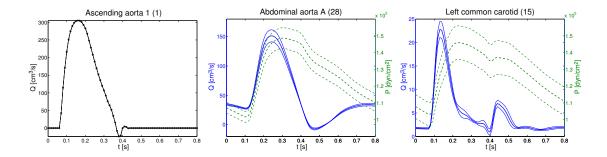


Figure 3.2: Imposed physiological flow rate for one heart beat (left), expectation with deformation by standard deviation of flow rate and pressure at the locations 28 and 15 during the sixth heart beat

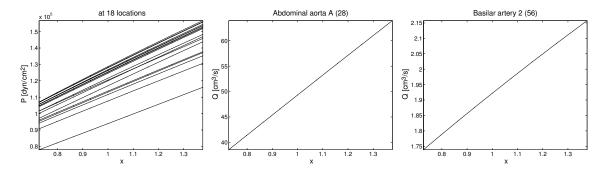


Figure 3.3: The dependence of pressure (left) and flow rate with respect to the random variable X

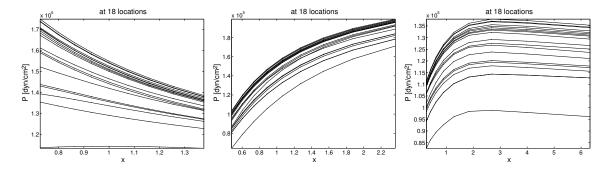


Figure 3.4: The dependence of pressure with respect to different random variables X accounting for the uncertainties of the parameters area A_0 (left), resistance R (middle) and Young modulus E (right)

The prescribed physiological flow rate for one heart beat is displayed on the left of Figure 3.2, which is randomized by a log-normal distributed random variable $X(\omega) = \exp(\mu_e + \sigma_v Y(\omega))$ (2.13) with $\mu_e = 0.01$, $\sigma_v = 0.1$ and Y follows standard normal distribution, see Figure 2.1. The statistics are computed via (2.20) and (2.22). The expectation $\mathbb{E}[\cdot]$ and expectation with deformation by standard deviation $\mathbb{E}[\cdot] - \mathbb{S}[\cdot]$ and $\mathbb{E}[\cdot] + \mathbb{S}[\cdot]$ of the flow rate and the pressure at the location of Abdominal aorta A (28) and Basilar artery 2 (58) are shown in Figure 3.2, from which we can observe that both quantities display some uncertainty effect due to the prescribed random flow rate and it has a relatively larger impact on the pressure than on the flow rate at both locations. Figure 3.3 depicts the dependence of pressure at all the locations and flow rate at two representative locations (magnitude is different at different locations), from which we can tell that the pressure and flow rate increase linearly with respect to the random variable X, which implies that in order to obtain accurate first (expectation) and second (variance) moments of the output, we only need a small level of interpolation by the

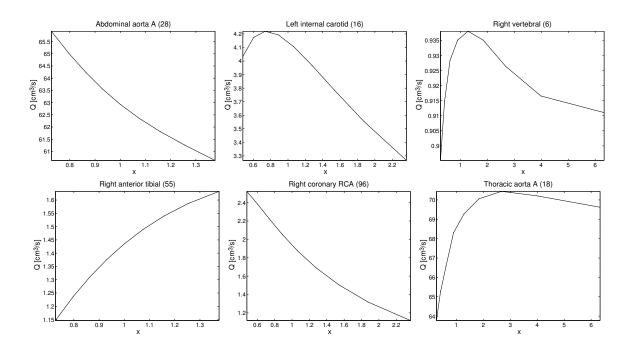


Figure 3.5: The dependence of flow rate with respect to different random variables X accounting for the uncertainties of the parameters area A_0 (left), resistance R (middle) and Young modulus E (right)

stochastic collocation method, which is verified from the relative error in Table 3.1, i.e. the error of the second level of interpolation is just slightly smaller than that of the first level of interpolation. ³

parameter	flow r	ate Q	area	A_0	re	sistance	R	Youn	g modulu	is E
level l	1	2	1	2	1	2	3	1	2	3
$\operatorname{error}(\mathbb{E}_{l}[Q])$	0.012	0.008	0.078	0.048	0.013	0.011	0.007	11.687	3.186	0.422
$\operatorname{error}(\mathbb{S}_l[Q])$	0.317	0.236	3.218	2.356	1.469	0.226	0.165	92.540	39.088	8.959
$\operatorname{error}(\mathbb{E}_l[P])$	0.003	0.002	0.011	0.007	0.003	0.003	0.002	1.677	0.492	0.075
$\operatorname{error}(\mathbb{S}_l[P])$	0.068	0.051	0.656	0.438	0.082	0.025	0.020	42.766	15.812	2.565

Table 3.1: A posteriori error of the statistics (3.1) for different parameters in different levels ($\times 10^{-3}$)

As for the geometrical parameter A_0 , terminal resistance R and Young modulus E, we use $(\mu_e = 0.01, \sigma_v = 0.1, 1/\text{SNR} \approx 10\%)$, $(\mu_e = 0.0625, \sigma_v = 0.25, 1/\text{SNR} \approx 25.4\%)$, $(\mu_e = 0.25, \sigma_v = 0.5, 1/\text{SNR} \approx 53.3\%)$, respectively, to distinguish the different degrees of uncertainties in (2.13). The dependence of pressure at all the locations and flow rate at some representative locations with respect to different uncertainties are shown in Figure 3.4 and 3.5. It is quite evident that all these quantities display nonlinear dependence on the uncertainties with high stochastic regularity. In particular, the pressure decreases as the area of the lumen increases and becomes more flat when the area becomes large enough, which is in accordance with physiological flow. On the other hand, the pressure increases as both the resistance and Young modulus increase, and start to slightly decrease when the Young modulus becomes large enough. Different from the pressure, the flow rate depends on the uncertainty

³From numerical perspective, we can see that it is sufficient for the first level of interpolation to compute the statistics of both the flow rate Q and the area A_0 with uncertainty in a small range $(1/\text{SNR} \approx 10\%)$ since the error in the second level is not quite different from that in the first level for all the four statistics $\mathbb{E}[Q], \mathbb{E}[Q], \mathbb{E}[P], \mathbb{E}[P]$. In contrast, for a relatively large range of uncertainty for resistance $(1/\text{SNR} \approx 25.4\%)$, the first level of interpolation is still sufficient for the first moment (expectation $\mathbb{E}[Q], \mathbb{E}[P]$) while the second level of interpolation is needed to have apparently more accurate second moment (standard deviation $\mathbb{S}[Q], \mathbb{S}[P]$). When the range of uncertainty is very large, as for Young modulus $(1/\text{SNR} \approx 53.3\%)$ with high non-linearity, we need high level of interpolation to evaluate accurately both the expectation and standard deviation as can be seen in Table 3.1 that the error between different levels of interpolation is far from each other for all the statistics.

in a distinct manner in different locations of the arterial tree for all the parameters as can be observed in Figure 3.5. This is verified from the value of the error $(\times 10^{-3})$ in Table 3.1, where the error of expectation and standard deviation of the flow rate Q is larger than that of the pressure P with the same level of interpolation for all the parameters.

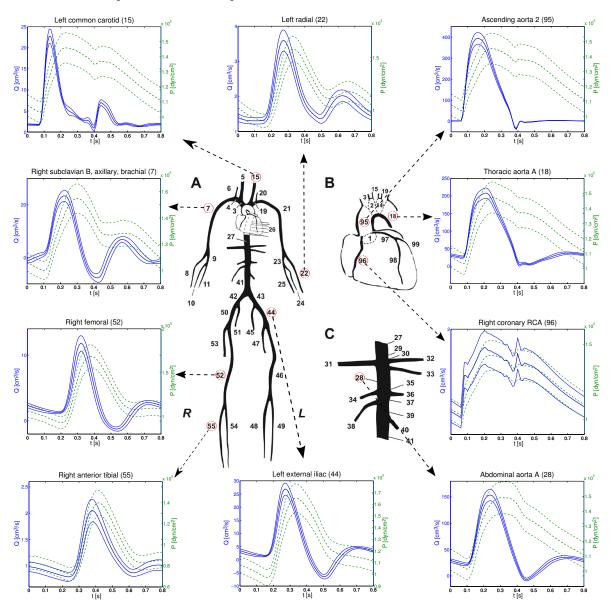


Figure 3.6: Expectation \mathbb{E} and expectation biased by standard deviation $\mathbb{E} - \mathbb{S}$ and $\mathbb{E} + \mathbb{S}$ of flow rate Q and pressure P at 10 representative locations in the main systemic arterial tree

3.3 Moderate dimensional parametric uncertainty

There are many different uncertainties from various sources entering into the coupled hyperbolic system (2.6), (2.9) and (2.10). For a systematic study of their importance, we parametrize them at first and conduct the global sensitivity analysis via (2.23). More specifically, we consider the following uncertainties:

1. Geometrical parameters: in our one dimensional model, we keep the length of each segment as a deterministic value to retain the geometry of the arterial tree and only consider the reference area

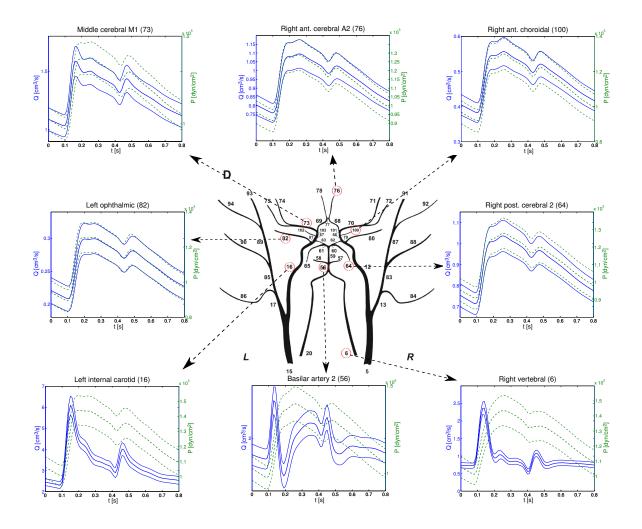


Figure 3.7: Expectation \mathbb{E} and expectation biased by standard deviation $\mathbb{E} - \mathbb{S}$ and $\mathbb{E} + \mathbb{S}$ of flow rate Q and pressure P at 8 representative locations in the cerebral arterial tree

 A_0 of the lumen as the uncertain parameter; we incorporate the uncertainty of wall thickness h into the elastic and viscoelastic term;

- 2. Mathematical and physical parameters: we randomize the blood density ρ and viscosity μ to account for the convection acceleration and wall friction effects, as well as Young modulus E and characteristic time T to account for the elastic and viscoelastic effects of the arterial wall (Poisson coefficient ν , wall thickness h and the characteristic angle ϕ in (2.5) are incorporated via E and T in each term);
- 3. Parameters from boundary conditions: the uncertainties arising from the prescribed flow rate Q at the proximal boundary of Ascending aorta 1 (1), the resistance R and the capacitance C in the lumped parameter model for the outflow boundary condition are taken into account;
- 4. External source or force term: we also consider the external pressure P_{ext} and the venous pressure P_v as the sources of uncertainties.

In order to distinguish the importance or impact of these uncertainties to the solution of the stochastic system (2.12), we parametrize them with the same signal-to-noise ratio via (2.13). ⁴

⁴For the sake of computational effort, we take $\mu_e = 0.01$, $\sigma_v = 0.1$ to obtain more accurate evaluation of the second statistical moment (e.g. variance, main effect in (2.23)) with small level of interpolation. Moreover, a small perturbation of these parameters will retain the mathematical property of the hyperbolic system. The Galerkin-Hermite quadrature

1			D	D	0	D	0	T	T.	1
location/parameter	ρ	μ	P_v	P_{ext}	Q	R	C	T	E	A_0
Right coronary RCA	0.014	0.023	6.160	0.008	66.106	21.027	0.008	0.000	1.153	3.882
Ascending aorta 2	0.000	0.000	0.003	0.000	99.029	0.003	0.000	0.000	0.001	0.001
Left common carotid	1.478	0.037	1.524	1.564	83.080	0.378	0.002	0.003	0.375	10.889
Left radial	0.798	0.023	4.901	0.006	81.959	8.073	0.010	0.001	0.992	0.762
Abdominal aorta A	0.001	0.020	2.424	0.004	88.786	7.160	0.004	0.000	0.364	0.742
Left external iliac	0.532	0.472	1.319	0.032	88.541	0.026	0.003	0.001	0.070	8.199
Right anterior tibial	5.800	0.017	6.678	0.004	48.924	0.263	0.006	0.002	0.890	32.780
Right femoral	4.034	0.033	4.218	0.002	63.342	0.568	0.004	0.001	0.225	24.624
Thoracic aorta A	0.012	0.007	1.431	0.001	92.374	4.845	0.002	0.000	0.214	0.958
Right subclavian B	0.326	0.023	0.371	0.001	98.266	0.097	0.001	0.000	0.186	0.600
Middle cerebral M1	5.127	0.037	7.668	0.037	48.197	0.441	0.005	0.002	0.994	32.178
Right ant. cerebral A2	0.373	0.037	8.081	0.017	69.693	17.358	0.008	0.002	1.041	0.051
Right ant. choroidal	0.918	0.033	7.996	0.011	71.901	12.751	0.008	0.002	1.063	1.447
Right post. cerebral 2	1.012	0.032	7.994	0.013	71.763	12.424	0.008	0.002	1.070	1.746
Basilar artery 2	0.078	0.106	19.926	1.014	42.325	28.395	0.002	0.022	0.232	0.216
Right vertebral	0.017	0.122	21.231	1.050	39.545	30.231	0.000	0.088	0.035	0.061
Left internal carotid	2.535	0.178	2.383	3.642	73.195	1.230	0.010	0.013	1.595	13.718
Left ophthalmic	4.938	0.021	8.601	0.014	51.741	1.123	0.006	0.010	1.180	26.415

Table 3.2: Sensitivity analysis: main effect of different parameters to flow rate Q at 18 locations (%)

location/parameter	ρ	μ	P_v	P_{ext}	Q	R	C	T	E	A_0
Right coronary RCA	0.051	0.049	6.576	0.071	62.169	22.661	0.007	0.000	1.236	5.541
Ascending aorta 2	0.086	0.046	6.496	0.070	62.034	21.776	0.007	0.001	1.296	6.661
Left common carotid	0.083	0.046	6.845	0.068	62.171	21.443	0.007	0.000	1.232	6.479
Left radial	0.048	0.072	5.649	0.087	61.563	28.581	0.008	0.000	0.964	1.124
Abdominal aorta A	0.063	0.044	6.817	0.071	62.062	22.567	0.007	0.000	1.180	5.544
Left external iliac	0.030	0.052	6.935	0.073	62.488	22.883	0.007	0.000	1.071	4.690
Right anterior tibial	0.892	0.111	4.641	0.125	52.807	36.620	0.006	0.001	0.838	1.484
Right femoral	0.002	0.059	6.542	0.079	62.634	24.732	0.007	0.000	1.016	3.067
Thoracic aorta A	0.082	0.046	6.763	0.069	62.152	21.556	0.007	0.000	1.240	6.481
Right subclavian B	0.063	0.047	7.385	0.069	62.502	21.195	0.007	0.000	1.104	5.820
Middle cerebral M1	0.010	0.043	7.444	0.217	62.326	23.554	0.007	0.001	1.011	3.365
Right ant. cerebral A2	0.103	0.058	7.140	0.135	60.341	28.427	0.007	0.001	0.911	0.333
Right ant. choroidal	0.074	0.061	7.161	0.100	60.791	27.859	0.007	0.001	0.919	0.547
Right post. cerebral 2	0.146	0.066	7.104	0.110	59.873	28.980	0.007	0.001	0.907	0.181
Basilar artery 2	0.001	0.057	6.483	0.101	62.221	25.149	0.007	0.001	1.083	3.080
Right vertebral	0.041	0.048	7.000	0.078	62.399	22.382	0.007	0.000	1.140	5.158
Left internal carotid	0.046	0.051	6.909	0.058	62.405	22.319	0.007	0.000	1.142	5.339
Left ophthalmic	0.116	0.076	8.085	0.055	60.976	26.420	0.006	0.001	0.905	0.420

Table 3.3: Sensitivity analysis: main effect of different parameters to pressure P at 18 locations (%)

Expectation ($\mathbb{E}[\cdot]$) and expectation biased by standard deviation ($\mathbb{E}[\cdot] - \mathbb{S}[\cdot]$ and $\mathbb{E}[\cdot] + \mathbb{S}[\cdot]$) of the blood flow rate and pressure is shown at the 18 representative locations in Figure 3.6 for the systemic main arterial tree and Figure 3.7 for the cerebral arterial tree. From both these two figures, we observe a good overall agreement in both wave shape and amplitude of the blood flow rate and pressure between the expectation of our simulation and the model prediction in [34], which is validated in high accordance with clinical averaged measurements. In particular, all the primary and secondary

abscissas are used as the collocation nodes for the stochastic collocation method with Smolyak sparse grid interpolation formula (2.17), where K = 10 and we use the first (q - K = 1) and second (q - K = 2) levels of interpolation with 21 and 241 collocation nodes respectively to compute the statistics (2.20) (2.22) and sensitivity (2.23).

The relative error as defined in (3.1) between the two levels of interpolation for the statistics of $\mathbb{E}[Q], \mathbb{E}[Q], \mathbb{E}[P], \mathbb{S}[P]$ are 2.29%, 8.69%, 0.38%, 1.59%, respectively, which are small enough even for the second moment of standard deviation. The small relative error implies that the first level of interpolation is sufficient to evaluate the statistics and also the second moment of main effect (2.23). We note that all the results we discuss below are evaluated from the second level of interpolation.

wave shape features of the blood flow from averaged measurement are well captured by our simulations.

Beside the significant similarity between the measurement and the simulation, as both observed in [34] and our work, another important observation from our stochastic simulation is that large variation of the blood flow occurs near the peak of flow wave during the systolic period (see, e.g., Ascending aorta 2 (95), Thoracic aorta A (18), Abdominal aorta A (28)), while the variation of pressure is not that different during the whole heart beat at most of the locations (e.g. Left radial (22), Left common carotid (15)). This observation is well verified from the measurements with also similar amplitude of variation (see Fig. 4 and 5 in [34] for the corresponding specific locations) and implies that the difference of blood flow and pressure wave propagation among different people arises probably from the kind of uncertainties we are investigating.

We compute the main effect of each parameter to the blood flow rate and pressure averaged over one heart beat at the 18 representative locations via the global sensitivity index in formula (2.23), with the results (value in percent (%)) shown in Table 3.2 for flow rate and 3.3 for pressure, from which we have the following observations:

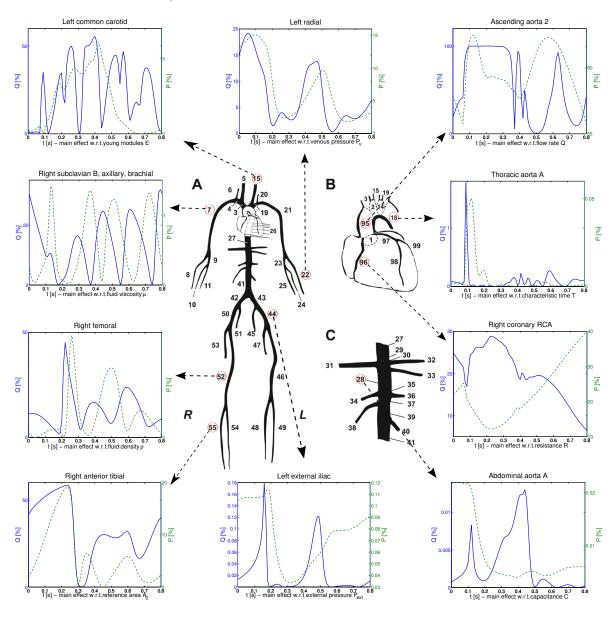


Figure 3.8: Time dependent main effect (global sensitivity index defined in (2.23)) over one heart beat at 10 representative locations in the main systemic arterial tree

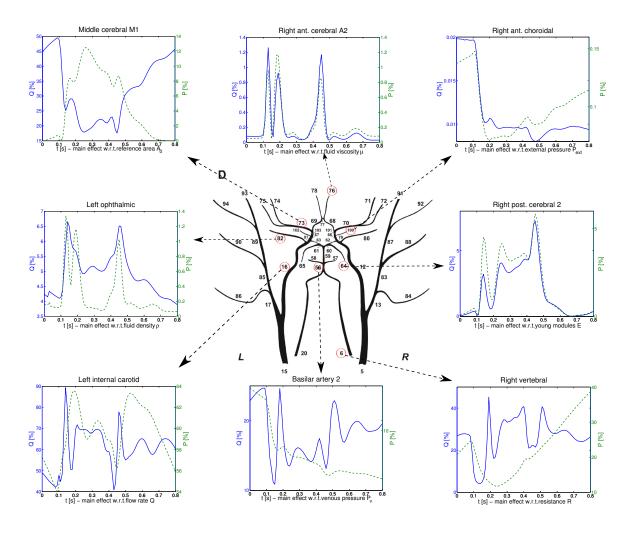


Figure 3.9: Time dependent main effect (global sensitivity index defined in (2.23)) over one heart beat at 8 representative locations in the cerebral arterial tree

- 1. From the main effect for both flow rate and pressure, we can see that the uncertainty arising from the imposed flow rate Q at the inflow boundary (prescribed heart flow rate) dominates all the other uncertainties as for the overall impact to the simulation results. In particular, it accounts for almost all the effect (around 99.0%, 98.3% and 92.4%) to the uncertainty of flow rate at the Ascending aorta 2 (95), Right subclavian B (7) and Thoracic aorta A (18), respectively, being the locations very near to the heart;
- 2. Moreover, the effect of uncertainty arising from the imposed heart flow rate is more evident to the systemic main arterial tree compared to the cerebral arterial tree, which can be observed from the value 39.5% location of the branching Right vertebral (6), although it is also very near the heart. It plays also a relatively small role in the most distal arterial segment after many branching, Right anterior tibial (55), taking around 48.9% effect;
- 3. However, this uncertainty does not have so evident and different effects on the pressure (staying around 60% for both the systemic main arterial tree and the cerebral arterial tree, with an exception 52.8% from the most distal arterial segment Right anterior tibial) as that on the flow rate. In fact, all the uncertainties display a relatively larger variation at different locations for the flow rate than for the pressure, as can be observed quite evidently from Table 3.2 and 3.3;
- 4. The next most important source of uncertainty for the flow rate are different at different locations, for instance, the reference area A_0 for the distal and relatively long arterial segments

including Right anterior tibial (55), Right femoral (52), Middle cerebral M1 (73) and Left ophthalmic (82); resistance R for the distal arterial segment directly coupled with lumped parameter model such as Right coronary RCA (96), or coupled indirectly but with many lumped parameter models, such as Right vertebral (6) and Basilar artery (2)

- 5. The next most important source of uncertainty for the pressure, in both the systemic main arterial tree and the cerebral arterial tree is resistance R, followed by venous pressure P_v and then reference area A_0 . All the other sources of uncertainty play very small role in the influence of pressure, with general decreasing order: Young modulus E > density $\rho >$ external pressure $P_{ext} >$ viscosity $\mu >$ capacitance C > characteristic time T;
- 6. As for the uncertainty arising from physical parameters ρ , μ , E, T, they are not so important as the parameters analyzed above for both flow rate and pressure. Relatively speaking, uncertainty of density for the convective acceleration effect at the distal and long arterial segments is evident; Young modulus for the elastic term is also evident at these places and is more important than characteristic time accounting for the viscoelastic term.

In order to have a closer look at the sensitivity of flow rate with respect to all of the uncertainties at different time of one heart beat, we compute the variation in time of the sensitivity (time dependent main effect) of different sources of uncertainties at different locations. We pick the most important source of uncertainty in general according to Table 3.2, e.g. imposed heart flow rate Q, at the most evident location, e.g. Ascending aorta 2 (95), and then the second most important source at the second most evident location and so on. Following this order we plot the Figure 3.8 and 3.9 for the time dependent main effect, which delivers more information about the uncertainty impact at different time. More specifically, we can draw the following conclusions:

- 1. The main effect (global sensitivity in time) of most of the parametric uncertainties varies in a large range within one heart beat. The variation of the main effect of some uncertainties is quite different or even opposite for flow rate and pressure, e.g. resistance R at Right coronary RCA (96) or reference area A_0 at Middle cerebral M1 (73), and changes in a similar way for some other uncertainties, e.g. Young modulus E at Right post.cerebral 2 (64) or venous pressure P_v at Left radial (22);
- 2. The large variation of the main effect occurs at some common time, especially at the beginning of systolic period and end of the diastolic period, e.g. flow rate Q at Ascending aorta 2 (95) or characteristic time T at Thoracic aorta A (18), or at the time of maximum or minimum flow rate during the systolic and diastolic periods, e.g. fluid density ρ at Left ophthalmic (82) or fluid viscosity μ at Right ant. cerebral A2 (76);
- 3. The evident main effect of most of the uncertainties span in a relatively large time range over one heart beat, e.g. flow rate Q at Ascending aorta 2 (95) or Young modulus E at Left common carotid (15), while for some other few uncertainties, it restricts at a small local time with peaks, e.g. characteristic time T at Thoracic aorta A (18) or fluid viscosity μ at Right ant. cerebral A2 (76).
- 4. In general, even though some uncertainties dominate the others, as observed from the main effect with averaged time in Table 3.2 and 3.3, from the variation of the main effect in time we can see that quite a few uncertainties play a near important role in an oscillating way. This suggests that when considering impact of uncertainty at local time, it would be misleading to overemphasize some uncertainties and neglect some others.

3.4 High dimensional parametric uncertainty

For systematic quantification of the impact of different uncertainties, it is reasonable to use the same probability distribution for one uncertainty in the global arterial network. However, in order to quantify some uncertainty arising from the same source but at different locations, it is more realistic to employ independent random variables to characterize the uncertainty at each of the location. In this section, we take two of the influential uncertainties for the blood pressure wave propagation (see

Table 3.3), resistance R at the 47 different distal boundaries and cross section reference area A_0 in the 103 different arterial segments of the schematic representation of the human arterial tree in Figure 3.1, and assign independent random variables to each of them at different locations to study locally the impact of uncertainties.

location/order	1st	2nd	3rd	4th	5th	1-5
Right coronary RCA	98.010 (96)	0.579(34)	0.385(36)	0.383(38)	0.288(26)	99.645
Ascending aorta 2	33.864(99)	22.409(98)	20.864(96)	6.975(34)	4.649(36)	88.762
Left common carotid	16.781(34)	11.166 (36)	11.142(38)	9.760(78)	8.225(26)	57.074
Left radial	96.782(22)	0.923(34)	0.613(36)	0.612(38)	0.459(26)	99.389
Abdominal aorta A	35.757(34)	23.834(36)	23.802(38)	6.727(26)	2.027(33)	92.147
Left external iliac	64.780(47)	14.886(48)	4.873(34)	4.369(49)	3.291(38)	92.198
Right anterior tibial	92.143(55)	2.066(34)	1.403(38)	1.395(36)	1.044(54)	98.051
Right femoral	65.185(54)	19.086(55)	4.749(34)	3.213(38)	3.200(36)	95.434
Thoracic aorta A	28.948(34)	19.304(36)	19.281 (38)	13.910(26)	4.030(33)	85.472
Right subclavian B	47.514(8)	38.477(11)	4.160(34)	2.767(36)	2.761(38)	95.680
Middle cerebral M1	45.862 (75)	44.636 (74)	2.839 (34)	1.886 (36)	1.881 (38)	97.103
Right ant. cerebral A2	98.004(76)	0.569(34)	0.378(36)	0.377(38)	0.283(26)	99.610
Right ant. choroidal	97.686 (100)	0.670(34)	0.445(36)	0.443(38)	0.334(26)	99.577
Right post. cerebral 2	97.666(64)	0.670(34)	0.445(36)	0.444(38)	0.334(26)	99.560
Basilar artery 2	34.116(65)	34.053(64)	12.039(58)	12.039(57)	1.273(34)	93.520
Right vertebral	34.364 (65)	34.298(64)	12.124(58)	12.124(57)	1.166 (78)	94.075
Left internal carotid	23.796(78)	10.593 (102)	10.019(34)	8.436 (75)	8.303(76)	61.147
Left ophthalmic	95.852 (82)	1.232 (34)	0.819 (36)	0.817 (38)	0.615(26)	99.336

Table 3.4: The largest five values and their summation of main effect (value in percent (%)) of flow rate with respect to resistance from their corresponding boundaries in bracket (\cdot) at 18 locations

location/order	1st	2nd	3rd	4th	5th	1-5
Right coronary RCA	29.782(34)	19.783 (36)	19.725 (38)	14.823 (26)	4.135(33)	88.248
Ascending aorta 2	30.395(34)	20.190 (36)	20.131 (38)	15.127(26)	4.219(33)	90.063
Left common carotid	30.390(34)	20.186(36)	20.127(38)	15.129(26)	4.219(33)	90.051
Left radial	24.430(22)	22.267(34)	14.790(36)	14.747(38)	11.115(26)	87.350
Abdominal aorta A	30.959(34)	20.557(36)	20.491(38)	14.091(26)	4.251(33)	90.350
Left external iliac	30.371(34)	20.597(38)	20.478(36)	13.650(26)	4.133(33)	89.229
Right anterior tibial	53.200(55)	12.236(34)	8.317(38)	8.264(36)	6.540(54)	88.556
Right femoral	29.180(34)	19.806(38)	19.688(36)	13.052(26)	3.972(33)	85.698
Thoracic aorta A	30.403(34)	20.194(36)	20.134(38)	15.138(26)	4.221(33)	90.091
Right subclavian B	30.117(34)	20.007(36)	19.952 (38)	14.996(26)	4.179(33)	89.252
Middle cerebral M1	29.744 (34)	19.757 (36)	19.699 (38)	14.814 (26)	4.129 (33)	88.143
Right ant. cerebral A2	24.067 (76)	22.659(34)	15.050(36)	15.005(38)	11.286 (26)	88.067
Right ant. choroidal	23.451(34)	21.853 (100)	15.578(36)	15.532(38)	11.681 (26)	88.094
Right post. cerebral 2	27.227(64)	21.695(34)	14.411 (36)	14.369(38)	10.805(26)	88.506
Basilar artery 2	29.461(34)	19.569(36)	19.512(38)	14.668 (26)	4.090(33)	87.300
Right vertebral	30.179(34)	20.047(36)	19.989(38)	15.023(26)	4.190(33)	89.429
Left internal carotid	30.228(34)	20.079(36)	20.020(38)	15.053(26)	4.197(33)	89.576
Left ophthalmic	24.635 (34)	17.590 (82)	16.356 (36)	16.308 (38)	12.280 (26)	87.168

Table 3.5: The largest five values and their summation of main effect (value in percent (%)) of pressure with respect to resistance from their corresponding boundaries in bracket (\cdot) at 18 locations

We assume that the resistance at the mth distal boundary is randomized by (2.13) as

$$R_m(\omega) = \exp(\mu_e + \sigma_v Y_m(\omega)) R_m, 1 \le m \le M, \tag{3.2}$$

where $Y_m, 1 \leq m \leq M$ are independent random variables obeying standard distribution.

The largest five values of the main effect ⁵ and their total weight (in percent (%)) is shown in

⁵We choose $\mu_e = 0.01, \sigma_v = 0.1$ for the sake of computational effort and accurate evaluation of the statistics and

Table 3.4 and 3.5, from which we can observe that the largest impact of the uncertainty comes from the nearest distal boundary for the flow rate, e.g. the impact to Right anterior tibial (55) comes from its distal boundary, while it comes mostly from the distal boundaries in the middle of the arterial tree (34, 36, 38, 33) for the pressure. In particular, the uncertainty of resistance at the distal boundaries of the coronary arterial tree (99, 98, 96) has a big impact for the Ascending aorta 2 (95) for flow rate while it still comes from (34, 36, 38, 33) for pressure, which indicates that we need to model this region with more detailed geometry and precise measurement in order to study the pressure wave propagation.

location/order	1st	2nd	3rd	4th	5th	1-5
Right coronary RCA	45.498 (96)	13.333(27)	9.516(95)	4.743(18)	4.091(21)	77.181
Ascending aorta 2	77.616 (95)	7.039(1)	5.138 (98)	1.907(27)	1.225(46)	92.925
Left common carotid	58.289(16)	10.457(12)	7.408(15)	3.479(69)	3.311(68)	82.943
Left radial	89.126 (22)	2.912(21)	2.443(27)	1.362(95)	0.994(7)	96.837
Abdominal aorta A	15.811 (95)	10.886(7)	10.786(21)	8.570(52)	8.570(46)	54.623
Left external iliac	46.320(46)	22.054(49)	19.212(48)	4.457(44)	1.769(47)	93.811
Right anterior tibial	92.292(55)	6.218(52)	0.329(54)	0.318(95)	0.181(7)	99.338
Right femoral	33.939(55)	32.890(52)	29.903(54)	0.629(7)	0.566 (95)	97.927
Thoracic aorta A	25.131(95)	13.627(21)	12.261(7)	8.885(14)	4.138(15)	64.042
Right subclavian B	32.805(11)	29.928(7)	26.728(8)	2.912(21)	1.692(27)	94.065
Middle cerebral M1	48.828 (74)	48.447 (75)	0.820 (16)	0.479(27)	0.325 (95)	98.898
Right ant. cerebral A2	75.245 (76)	4.403(27)	3.530(12)	3.005(95)	2.095(68)	88.277
Right ant. choroidal	91.213 (100)	2.504(12)	1.562(27)	1.069(95)	0.604(9)	96.953
Right post. cerebral 2	91.862(64)	1.878(27)	1.287(95)	0.743(21)	0.670(18)	96.441
Basilar artery 2	27.970(9)	18.040(20)	15.745 (16)	15.338(6)	15.088(12)	92.181
Right vertebral	63.532(6)	19.705(20)	6.048(9)	3.454(16)	3.319(12)	96.058
Left internal carotid	62.295(16)	11.773(12)	4.017(69)	3.794(68)	3.604(74)	85.483
Left ophthalmic	98.458 (82)	0.491 (16)	0.267(27)	0.180 (95)	0.096 (9)	99.492

Table 3.6: The largest five values and their summation of main effect (value in percent (%)) of flow rate with respect to reference area from their corresponding boundaries in bracket (\cdot) at 18 locations

location/order	1st	2nd	3rd	$4\mathrm{th}$	$5\mathrm{th}$	1-5
Right coronary RCA	22.474(27)	16.051 (95)	8.012(18)	7.522(96)	7.005(21)	61.064
Ascending aorta 2	24.309(27)	16.979 (95)	8.655(18)	7.586(21)	7.217(7)	64.745
Left common carotid	24.982(27)	16.981 (95)	8.859(18)	7.841(21)	7.411(7)	66.074
Left radial	44.965(22)	13.821(21)	12.215(27)	7.231(95)	3.974(7)	82.208
Abdominal aorta A	22.207(95)	10.407(21)	9.691(7)	8.295(18)	8.071(9)	58.672
Left external iliac	23.361(95)	12.058(21)	11.785(7)	9.017 (18)	7.659(14)	63.880
Right anterior tibial	50.087(55)	40.073(52)	2.088(95)	2.007(54)	1.093(7)	95.347
Right femoral	27.526(52)	15.743 (95)	8.293 (7)	8.136 (21)	6.052(18)	65.751
Thoracic aorta A	25.402(27)	17.153(95)	8.025(21)	7.539(7)	7.500 (18)	65.618
Right subclavian B	26.990(27)	17.276 (95)	9.161(18)	8.645(21)	6.995(9)	69.067
Middle cerebral M1	28.971 (16)	16.817 (27)	11.438 (95)	6.024 (18)	5.665 (9)	68.915
Right ant. cerebral A2	46.297 (76)	9.406(27)	7.563(12)	6.424(95)	4.490 (68)	74.180
Right ant. choroidal	59.741 (100)	11.213 (12)	6.968(27)	4.773(95)	2.701(9)	85.396
Right post. cerebral 2	63.271(64)	8.232(27)	5.648(95)	3.260(21)	2.936(18)	83.346
Basilar artery 2	21.416(27)	14.728 (95)	8.760 (21)	7.740(7)	7.629(18)	60.272
Right vertebral	23.829(27)	16.475 (95)	10.724(7)	8.473(18)	8.384 (21)	67.885
Left internal carotid	24.066(27)	16.355 (95)	8.579(18)	7.691(21)	7.295(7)	63.987
Left ophthalmic	62.446 (82)	11.727 (16)	6.309(27)	4.281 (95)	2.287(9)	87.050

Table 3.7: The largest five values and their summation of main effect (value in percent (%)) of pressure with respect to reference area from their corresponding boundaries in bracket (\cdot) at 18 locations

sensitivity with small level of interpolation. By the main effect formula (2.23) and Smolyak sparse grid collocation method (2.17) with the first level of interpolation q - K = 1, we compute main sensitivity at the 18 representative locations with respect to each random resistance at the 47 distal boundaries.

As for the uncertainty quantification with respect to reference area A_0 , we take the same numerical design as for the resistance, leading to 103 independent random variables and 207 collocation nodes for the first level of interpolation. Similar data are shown in Table 3.6 for flow rate and 3.7 for pressure, from which we can see that the most important uncertainty for the flow rate at the representative locations comes from the nearest arterial segment, e.g. the main effect with the largest value 98.5% at Left ophthalmic (82) in the cerebral arterial tree is due to the uncertainty of the reference area of the arterial segment itself. An interesting observation is that the five largest values of main effect of the flow rate at the Abdominal aorta A (28) comes from the uncertainty of the reference area near the heart (Ascending aorta 2 (95)) as well as at the four longest peripheral arterial segments - the arms (7, 21) and legs (52, 46). At Left common carotid (15), the most important uncertainties lie symmetrically at the near Internal carotid (16, 12) and far Ant. cerebral 1 (69, 68) in the cerebral arterial tree as well as itself (15). The largest values of the main effect for the pressure concentrate again at the few locations (27, 95, 18) close to the heart, i.e. a small change of the cross section area of the large arteries near the heart leads to relatively large variation of pressure wave propagation in the global arterial network.

4 Concluding remarks

In this work we presented a general framework for uncertainty quantification in the human arterial network. We identified the main uncertainties arising from various sources and characterized them by random variables following certain specific probability distributions. Based on a one dimensional deterministic fluid structure interaction model (a system of nonlinear hyperbolic equation), we introduced the stochastic model by incorporating many different kinds of uncertainties into blood flow in arteries and its interaction with arterial walls in a human arterial network. One of the most efficient stochastic computational methods - the stochastic collocation method with Smolyak sparse grid - was applied to discretize the coupled stochastic hyperbolic system in stochastic space. In order to study the impact of these uncertainties on the blood flow and pressure wave propagation, we provided statistical and sensitivity analysis by evaluating and interpreting the expectation, standard deviation as well as the main effect accounting for global sensitivity.

Our method has been applied to analyze three different kinds of experiments: 1, one dimensional parametric uncertainty to examine the stochastic regularity and nonlinearity of the solution with respect to different uncertainties as well as the convergence analysis of the sparse grid stochastic collocation method; 2, moderate dimensional parametric uncertainty to make a systematic study of the impact of different uncertainties on the blood flow and pressure in some representative locations; 3, high dimensional parametric uncertainty to highlight the correlation of different local arterial segments for the impact of some uncertainty in the blood flow and pressure wave propagation. These experiments, especially the second one, provide the first systematic uncertainty quantification in human arterial network, with uncertainties arising from various sources and can be applied for more precise experimental design and measurement.

There are several limitations in our work that we would like to point out: 1, the probability distribution we used was assumed to be log-normal type independent of time and space, yet for more physiological uncertainty quantification, we need to calibrate realistic probability distribution according to more specific medical data; 2, the degree of uncertainty is restricted to be small with noise-to-signal around 10% in order to have more accurate evaluation of statistics with the first level of interpolation for high dimensional problems constrained by computational effort; 3, there are still many other facts that we didn't consider in our model, the arterial network being not as complete as possible, large arteries with strong local flow field not being suitably described (the use of a fully 3D model would be more appropriate in this case), etc. More research effort is needed to address these limitations, for instance, how to apply the optimal control or optimization strategy to calibrate the probability distribution for different uncertainties[14], how to reduce the stochastic computational effort and increase the accuracy of the numerical solutions by taking full advantage of a small sample of solutions and the structure of the stochastic manifold with reduced basis method [13].

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