aqualab

Quantum Imaging Sensors

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1. Light Detection and Ranging LiDAR

Classical LiDAR



From a <u>short burst</u> or pulse of light, one can get distance *d* from source to receiver

$$d = \frac{c \cdot TOF}{2}$$

Source: Alexis Rochas



3D reconstruction



T. Milanese et al., Digital SiPM with reconfigurable back-end for LiDAR applications, to be published.

2. Hidden scenes

Hidden scene behind camouflage



Laboratory fluorescent light (from top)



Halogen light (in front of the setup)

Hidden scene behind camouflage

- Single channel results.
- Gating applied on point cloud.



Hidden scene behind camouflage

 $\sum_{k=1}^{20} \sum_{i=1}^{20} \sum_{j=1}^{20} \sum_{j=1}^{20} \sum_{j=1}^{20} \sum_{i=1}^{20} \sum_{j=1}^{20} \sum_{$

















Moving the objects manually by simulation and applying then the net as a mask.

3. Non-Line-of-Sight LiDAR



Source: D. Faccio, Univ. of Glasgow

Principle of NLOS



Source: D. Faccio, Univ. of Glasgow



The Chameleon SPAD system

Chameleon NLOS Result

Non-confocal NLOS setup



Results using standard NLOS reconstruction algorithms



Future directions

Quantum imaging

Quantum imaging

- Quantum LiDAR
- Ghost imaging
- Quantum (ultra-fast) spectroscopy
- Quantum Raman spectroscopy
- Quantum distillation
- Quantum state tomography
- Quantum holography
- Quantum super-resolution
- Quantum plenoptic cameras
- Quanta burst photography

Entangled photons: time and spatial correlations

- Entangled photons must be anti-correlated in momentum and correlated in position
- In the far field, <u>Idler</u> and <u>Signal</u> photons are anti-symmetric (spatial coincidence)
- In the near field they are adjacent

Always: time coincident



Quantum LiDAR

- Goal: improvement of SNR in complex scenes
- Method
 - 1. Classical image = background
 - 2. Quantum image = object of interest
 - 3. Add time-of-flight and a reconstruction algorithm and this yields a quantum LiDAR

Quantum NLOS

Thank You

ANTER A

Dôtel

http://aqua.epfl.ch

1st User Group Meeting, Les Diablerets, 2022 Next UGM: Feb. 2026